What's in a neighborhood? Describing nodes in RDF graphs using shapes

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- 1. Introduction
- 2. Motivation for neighborhoods
- 3. Provenance polynomials
- 4. Causality
- 5. Desiderata for neighborhoods
- 6. Conclusion

Role of the schema in data management

- Traditional data modeling: **prescriptive** schema
 - data must conform
 - many advantages
- Web data, data integration: **descriptive** schema
 - express expected characteristics of data
 - in RDF graphs, such characteristics are known as **shapes**

RDF graphs

- Directed graphs with labels on edges
- Edge $x \rightarrow y$ with label p: triple (x, p, y)
 - x is called the **subject**
 - y is called the **object**
 - *p* is called the **property**
- Real RDF:
 - nodes can be of different kinds (IRI, blank, literal)
 - properties can also be nodes

Shapes in graph data

- Shape:
 - a unary **query** over RDF graphs
 - returns a set of nodes
 - a predicate on nodes of RDF graphs
 - node under consideration is called **focus node**
- Examples: let x denote the focus node
 - "x has a phone property, but no email"
 - "x has at least five managed-by edges"
 - "x has a path of friend-edges to the CEO of Apple"
 - "*x* has no other properties than name, address, and birthdate"

Shape languages

- In principle, could simply use SPARQL to express shapes
- Yet, two dedicated shape languages:

• SHACL

- Shapes Constraint Language
- <u>W3C Recommendation</u>
- logic-based, description logic style

• ShEx

- Shape Expressions
- <u>shex.io</u>
- automata/regex based

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- Returns a **subgraph**: all edges to and from the node
- "Ball of radius 1"

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DESCRIBE USING SHAPE?

- Balls $B^{G}(v, k)$ where k = 1, 2, ... give a concept of neighborhood that is **too crude**
- Using a shape σ , can we define a subgraph $B^G(v, \sigma)$?

Example:

- Let σ be "v has at least one email edge, and at most one name edge"
- What should $B^G(v, \sigma)$ consist of?
 - If v does not satisfy σ : the empty graph
 - Otherwise: intuition: at least one of the email edges. Anything else?

Motivations for neighborhoods

- **Provenance** for shapes: $B^{G}(v, \sigma)$ can serve an an **explanation** why v satisfies σ
- **Repairing** shape violations: if v does **not** satisfy σ , then $B^G(v, \neg \sigma)$ can point out edges that should be added
- Knowledge graph subsets [Labra Gayo et al.]: given a shape σ , build a subset of G by taking union of all $B^G(v, \sigma)$
 - Also known as "shape fragments" [EDBT 2023 paper on provenance for SHACL]
 - Basically, using shapes as a **retrieval** mechanism

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• Syntax of **shapes** ϕ :

 $\phi ::= \top | \perp | hasValue(c) | test(t) | eq(p,r) | disj(p,r) | closed(P)$ $| \phi \land \phi | \phi \lor \phi | \neg \phi | \ge_k p.\phi | \le_k p.\phi | \forall p.\phi$

• Semantics, node a in graph G satisfies ϕ if:

 $G, a \models \phi$ if: ϕ hasValue(c)a = ca satisfies ttest(t)the sets $\llbracket p \rrbracket^G(a)$ and $\llbracket r \rrbracket^G(a)$ are equal eq(p,r)the sets $\llbracket p \rrbracket^G(a)$ and $\llbracket r \rrbracket^G(a)$ are disjoint disj(p,r)for all triples $(s, p, o) \in G$ with s = a we have $p \in P$ closed(P) $#\{b \in \llbracket p \rrbracket^G(a) \mid G, b \models \psi\} \ge k$ $\geq_k p.\psi$ $#\{b \in \llbracket p \rrbracket^G(a) \mid G, b \models \psi\} \le k$ $\leq_k p.\psi$ every $b \in \llbracket p \rrbracket^G(a)$ satisfies $G, b \models \psi$ $\forall p.\psi$

SHACL RDF syntax vs SHACL logical syntax

- W3C SHACL has an RDF syntax of "shapes graphs"
 - RDF syntax allows exchange and management of schema information using standard Web tools
- Logical syntax proposal by Corman et al.
 - More convenient for writing complex shapes, logical analysis
 - Extended to cover the **full** SHACL specification
 - [Delva, Dimou, Jakubowski, Van den Bussche EDBT 2023]
- Tool SLS developed

:WorkshopShape sh:property [
 sh:path :author ; sh:qualifiedMinCount 1 ;
 sh:qualifiedValueShape [sh:class :Student]] .

Shapes graph in RDF



 \geq_1 :author . \geq_1 rdf:type . *hasValue*(:Student)

Logical syntax

https://github.com/MaximeJakubowski/sls_project

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• Syntax of **shapes** ϕ : *c*: constant

 $\phi ::= \top \mid \perp \mid hasValue(c) \mid test(t) \mid eq(p,r) \mid disj(p,r) \mid closed(P) \\ \mid \phi \land \phi \mid \phi \lor \phi \mid \neg \phi \mid \geq_k p.\phi \mid \leq_k p.\phi \mid \forall p.\phi$

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• Syntax of **shapes** ϕ : t: node test

 $\phi ::= \top | \perp | hasValue(c) | test(t) | eq(p,r) | disj(p,r) | closed(P)$ $| \phi \land \phi | \phi \lor \phi | \neg \phi | \ge_k p.\phi | \le_k p.\phi | \forall p.\phi$

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• Syntax of **shapes** ϕ :

p,r: properties

$$\phi ::= \top | \perp | hasValue(c) | test(t) | eq(p,r) | disj(p,r) | closed(P) | \phi \land \phi | \phi \lor \phi | \neg \phi | \ge_k p.\phi | \le_k p.\phi | \forall p.\phi$$

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• Syntax of **shapes** ϕ :

P: set of properties

- $\phi ::= \top \mid \perp \mid hasValue(c) \mid test(t) \mid eq(p,r) \mid disj(p,r) \mid closed(P)$ $\mid \phi \land \phi \mid \phi \lor \phi \mid \neg \phi \mid \geq_k p.\phi \mid \leq_k p.\phi \mid \forall p.\phi$
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Intermezzo: expressiveness of SHACL

- Each of *eq*, *disj*, *closed* is **primitive**
 - cannot be expressed in terms of the other language constructs
- We simplified a bit: SHACL allows regular expression **property paths** *E* and constraints eq(E, p) and disj(E, p)
 - Allowing even more general $eq(E_1, E_2)$ would **increase** expressive power
 - Same for $disj(E_1, E_2)$
- [Bogaerts, Jakubowski, Van den Bussche, ICDT and LMCS]
- **Recursion** is left unspecified in W3C Recommendation
 - can be added as in logic programming

Intermezzo: computing shape queries

- The **shape query** for a shape σ :
 - Input: an RDF graph G
 - Output: all nodes $v \in G$ such that $G, v \models \sigma$
- Dedicated SHACL engines exist, e.g., TopQuadrant
- SHACL can also be compiled to SPARQL [Corman et al.]
 - Without property paths, even to SQL [ISWC 2024]
- SHACL is strictly weaker than SPARQL
- Not expressible, focus node *x*:
 - "x is part of a 4-clique"
 - "x has more p-edges than r-edges"

Provenance polynomials

- Provenance polynomials for **database queries**:
 - v a result of a query Q on database D
 - pol(D, v, Q): compact representation of all proofs why $v \in Q(D)$
- Multivariate polynomial, unknowns are facts in D

Example: let Q be select R.A from R(A,B) join S(B)

 $pol(D, a, Q) = [a, b] \cdot [b] + [a, c] \cdot [c]$

• Known for positive relational algebra, first-order logic, Datalog

[Green, Karvounarakis, Tannen], [Grädel, Tannen], [Deutch, Milo, Roy, Tannen]



Provenance for SHACL

- [Dannert, Grädel]: provenance polynomials for ALC
 - Simplest description logic
 - Unknowns are triples
 - $pol(G, a, \phi_1 \land \phi_2) = pol(G, a, \phi_1) \cdot pol(G, a, \phi_2)$
 - $pol(G, a, \phi_1 \lor \phi_2) = pol(G, a, \phi_1) + pol(G, a, \phi_2)$
 - $pol(G, a, \exists p. \psi) = \sum_{(a,p,b) \in G} [a, p, b] \cdot pol(G, b, \psi)$
 - $pol(G, a, \forall p, \psi) = \prod_{(a, p, b) \in G} [a, p, b] \cdot pol(G, b, \psi)$
- Crucial property: a satisfies ϕ iff polynomial not zero
- We must extend this:
 - to **counting** qualifiers $\geq_k p.\psi$ and $\leq_k p.\psi$
 - to eq, disj, closed

Polynomials for $\geq_k p.\psi$ and $\leq_k p.\psi$

• Idea:

- $\geq_1 p.\psi$ is same as $\exists p.\psi$
- $\leq_0 p.\psi$ is same as $\forall p. \neg \psi$
- Adapt to larger k (see paper)



Example: $\phi = \leq_1 \text{auth.} \leq_0 \text{type.} hasValue(\text{stud})$

"x has at most one author who is not a student"

$$pol(G, c, \phi) = [c, \text{auth}, a_1] \cdot [a_1, \text{type, prof}] \cdot 0 + [c, \text{auth}, a_2] \cdot [a_2, \text{type, stud}] \cdot 1 = [c, \text{auth}, a_2] \cdot [a_2, \text{type, stud}]$$

Polynomials for *eq*, *disj*

• For *disj* and $\neg eq$, we also need negated triples (**absence** of triple)



$$pol(G_1, a, eq(p, r)) = [a, p, b] \cdot [a, r, b] \cdot [a, r, b] \cdot [a, p, b]$$

$$pol(G_2, a, disj(p, r)) = [a, p, b_1] \cdot [a, r, b_1] \cdot [a, r, b_2] \cdot [a, p, b_2]$$

$$pol(G_3, a, \neg disj(p, r)) = [a, p, b_2] \cdot [a, r, b_2]$$

$$pol(G_1, a, eq(p, r)) = [a, p, b_1] \cdot [a, r, b_1] + [a, r, b_3] \cdot [a, p, b_3]$$

From polynomials to neighborhoods

- Let $G, v \models \sigma$. How should we define $B(G, v, \sigma)$?
- *Btok*:
 - Calculate provenance polynomial $pol(G, v, \sigma)$
 - Return all positive triples occurring as unknowns (tokens) in the polynomial
 - We could also take **all** triples, both negative and positive
 - [Bogaerts, Jakubowski, Van den Bussche PODS 2024]
- **B**_{mon}:
 - Pick a monomial (term) from the polynomial
 - Return all triples in there
 - Non-deterministic!

B_{tok} and B_{mon}



- **Example:** $\phi = \leq_1 \text{auth.} \leq_0 \text{type.} hasValue(stud)$
 - $pol(G, c, \phi) = [c, auth, a_2] \cdot [a_2, type, stud]$
 - So, $B_{tok}(G, c, \phi) = B_{mon}(G, c, \phi) =$

$$c \xrightarrow{type} stud$$

- Example: $\sigma = \geq_1$ auth. T
 - $pol(G, c, \sigma) = [c, \text{auth}, a_1] + [c, \text{auth}, a_2]$ so $B_{tok}(G, c, \sigma) = \begin{bmatrix} auth & a_1 \\ c & auth & a_2 \end{bmatrix}$



• For $B_{mon}(G, c, \sigma)$ two possibilities:



Remark: computing





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Causality as alternative to provenance polynomials

- Neighborhood $B(G, v, \phi)$ is supposed to **explain** why $G, v \vDash \phi$
- B_{tok} and B_{mon} do that, in a sense (see later)
- Halpern-Pearl causality: formal definition of **cause** for $G, v \models \phi$
- **Supercause:** set C of positive, negative triples from G such that after "flipping" C in G, node v no longer satisfies ϕ
- Cause: minimal supercause
- Note: A repair for violating ϕ is the same as a cause of $\neg \phi$!
 - [Ahmetaj et al., ISWC 2022]

Causality: example

• We have $G_2, a \models disj(p, r)$



- {[*a*, *p*, *b*₂], [*a*, *p*, *b*₁]} is a **supercause**:
 - Flipping this in G_2 yields G'_2 : p and r no longer disjoint a'_3
 - Not a **cause**: deleted $[a, p, b_1]$ is unnecessary
 - The two (minimal) **causes** are:
 - $\{\overline{[a, p, b_2]}\}$ (insert $[a, p, b_2]$)
 - $\{\overline{[a,r,b_1]}\}$ (insert $[a,r,b_1]$)

Neighborhoods by causality?

- Tempting to define a neighborhood to be a cause
 - We will see soon this is not "sufficient"
- What **does** work: from B_{tok} , only keep **causally relevant** triples
 - Belonging to some cause
 - High computational complexity

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Is there a "best" definition of neighborhood?

- No. Several desiderata, incompatible.
- Sufficiency: Natural desidaratum in provenance research [Glavic]
 - If $G, v \vDash \sigma$, then also $B(G, v, \sigma), v \vDash \sigma$
 - "Node v should still satisfy the shape in its shape neighborhood"
- **Theorem:** *B*_{tok}, *B*_{mon}, and causally relevant restrictions, are sufficient
- Determinism
- Minimality, e.g., minimally sufficient neighborhoods
 - not deterministic: "focus node has at least an email **or** a phone property"
- [Bogaerts, Jakubowski, Van den Bussche PODS 2024]

Conclusions and further research

- Shapes can be used for **more** than descriptive schemas
- Retrieve subgraphs!
- No single approach is "best", but we can follow some **principles**
- 1. Extend SHACL to full RDF (where properties can be nodes)
 - Or even RDF-star?
- 2. Neighborhoods for property paths
 - Can become very large
- 3. Empirical research needed why SHACL is "better" than SPARQL
 - Theoretical complexity is lower
- 4. Compare SHACL neighborhoods to ShEx neighborhoods [Labra Gayo et al.]

References—thanks Bart Bogaerts, Thomas Delva, Anastasia Dimou

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